

Diámetro continuo en grafos

Delia Garijo

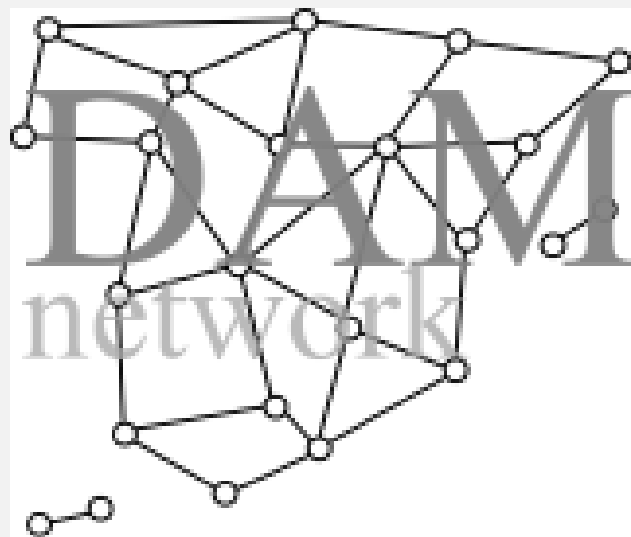
Universidad de Sevilla

Sesión Especial de Matemática Discreta y Algorítmica
Congreso Bienal de la RSME 2024

Diámetro continuo en grafos

Delia Garijo

Universidad de Sevilla



Colaboraciones con:

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Sergio Cabello | U. Ljubljana

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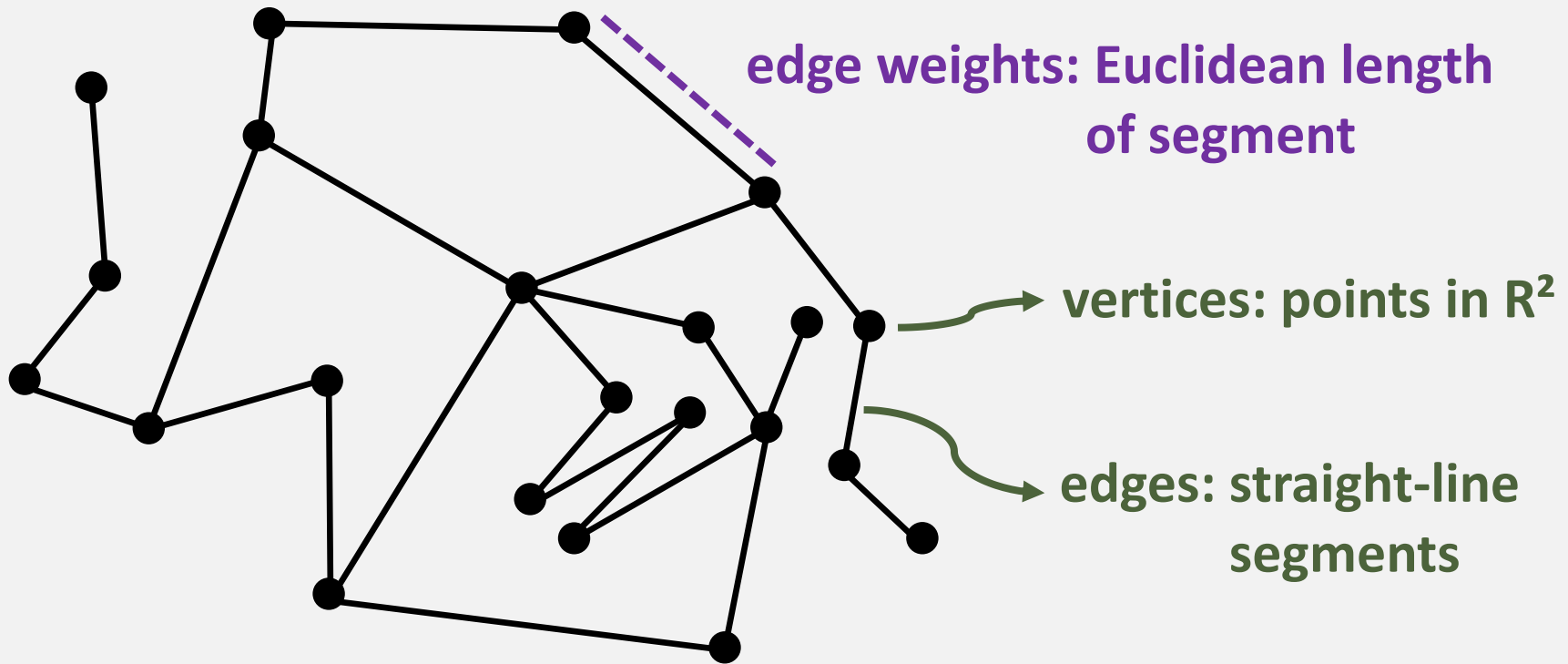
Fabian Klute | UPC

Irene Parada | UPC

Rodrigo I. Silveira | UPC

Our object:

A realization of a graph in some Euclidean space



edge weights: Euclidean length
of segment

vertices: points in \mathbb{R}^2

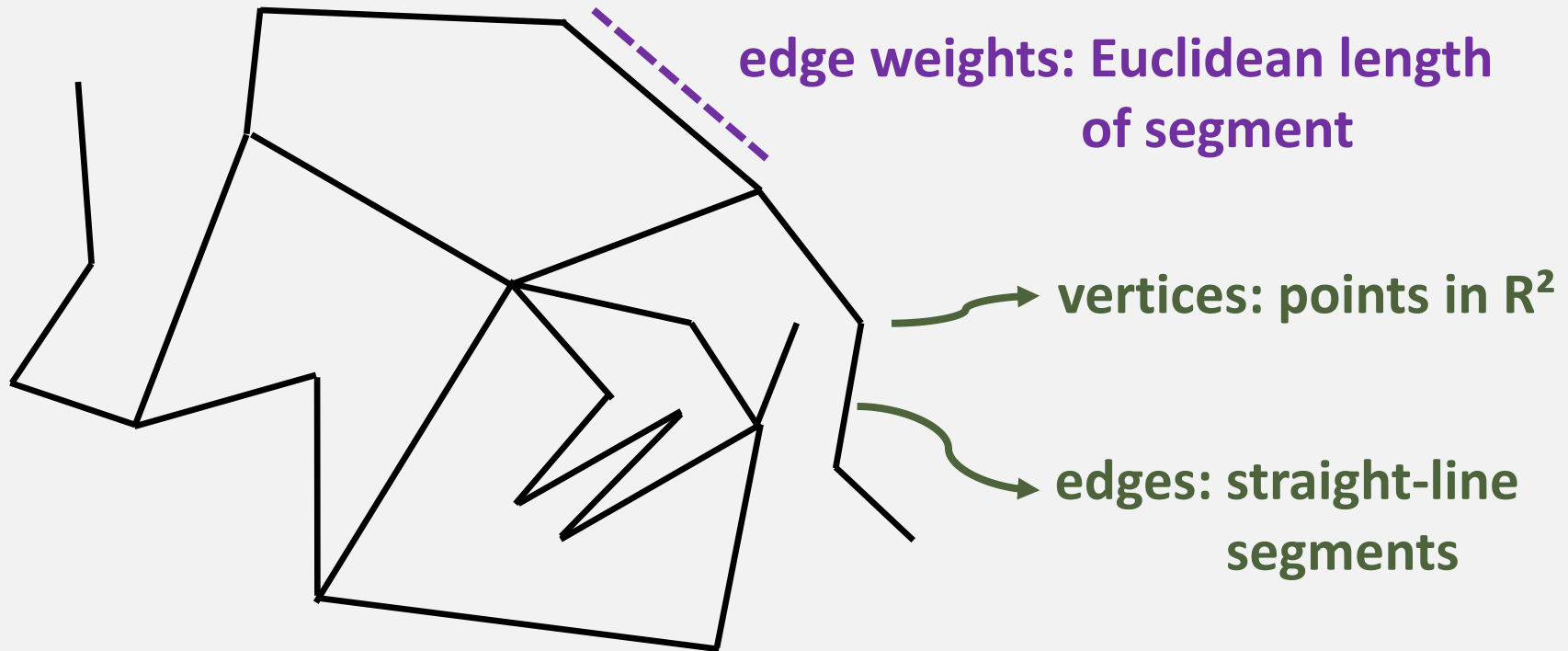
edges: straight-line
segments

No crossings between edges

Plane geometric graph

Our object:

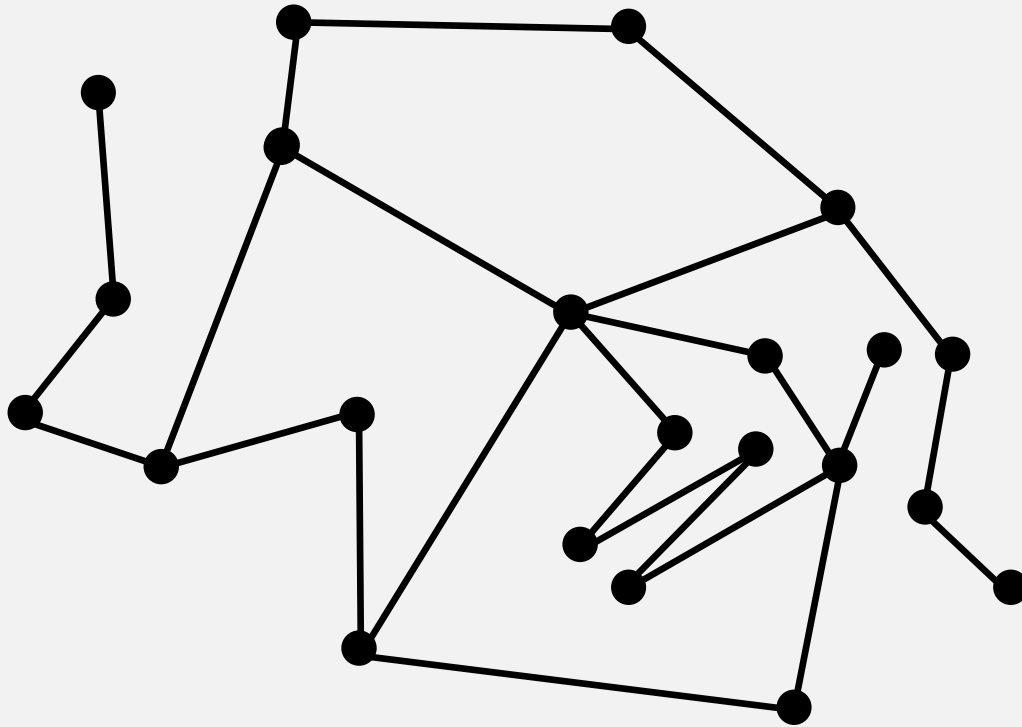
A realization of a graph in some Euclidean space



No crossings between edges

The **LOCUS** of a plane geometric graph

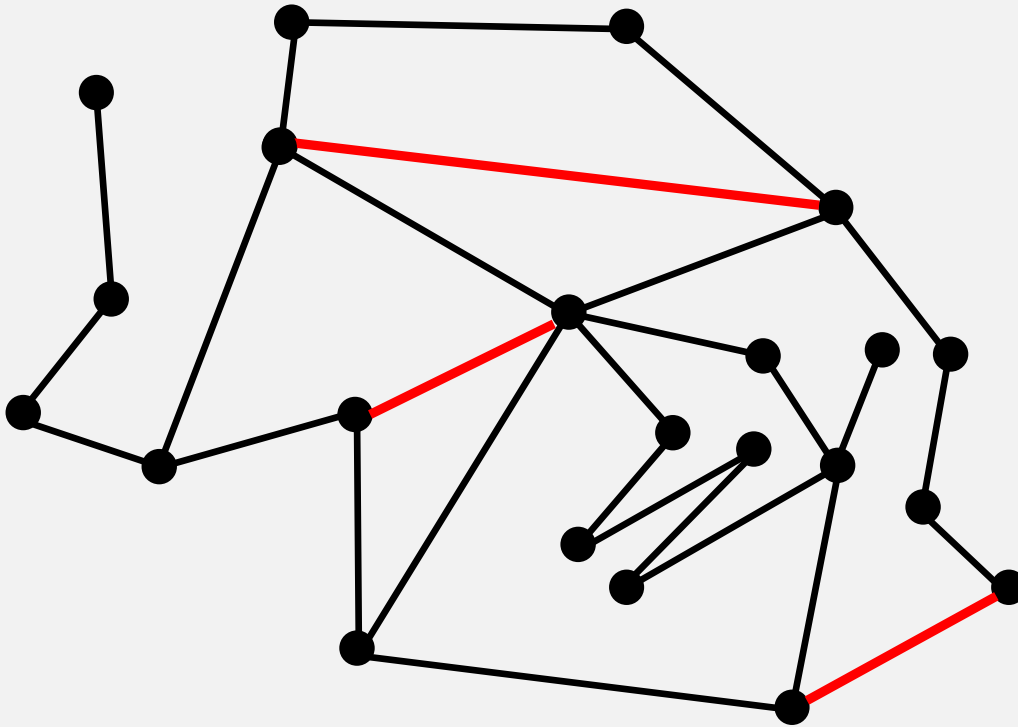
Goal: “improve” a graph



Goal: “improve” a graph

by adding edges

distances



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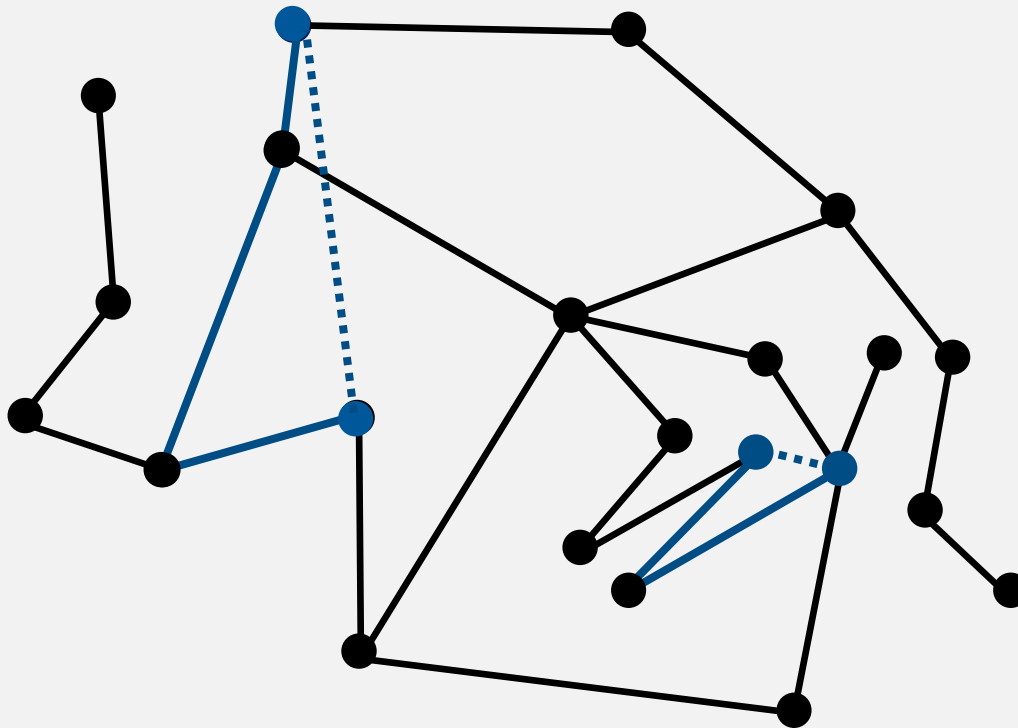


distances



dilation

(max detour between vertices)



Goal: “improve” a graph

by adding edges



distances

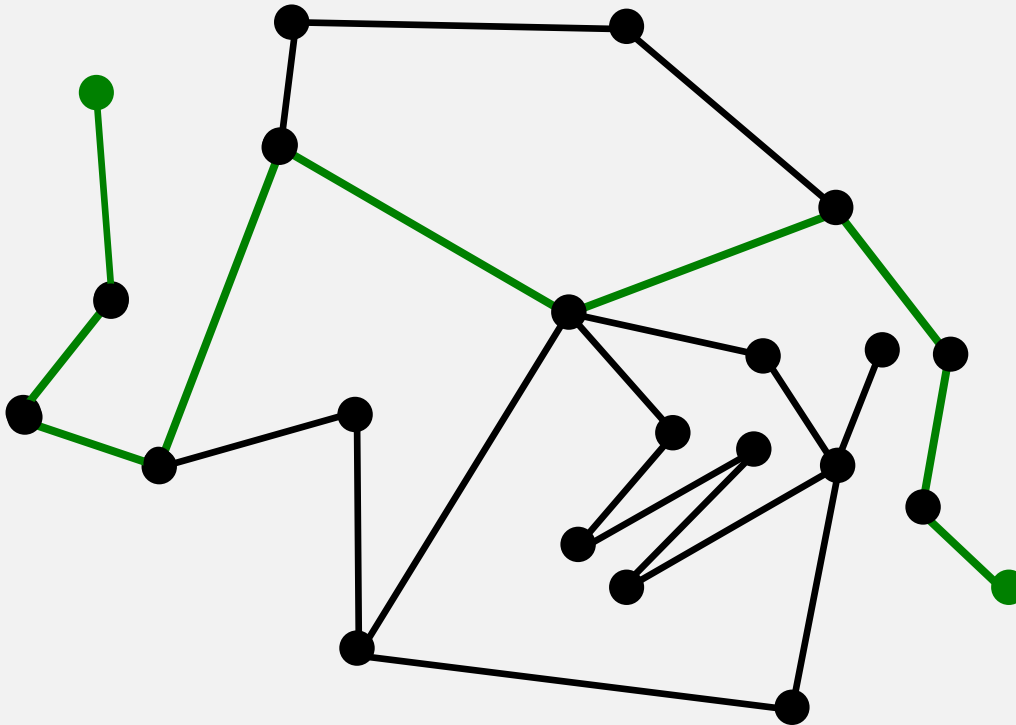


dilation

(max detour between vertices)

diameter

(max distance between vertices)



Goal: “improve” a graph

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distances



dilation

(max detour between vertices)

diameter

Optimal k-augmentation problem:

(max distance between vertices)

Insert k additional edges to minimize some measure on the resulting graph

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distances



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Optimal k-augmentation problem:

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Adding one edge/diameter:

Grobe et al., 2015 (trees embedded in a metric space)

Wang, 2017 (paths embedded in a metric space)

Biló, 2018 (trees embedded in a metric space)

Wang and Zhao, 2021 (unicycle graphs and
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Adding k edges/diameter:

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plane Euclidean graphs in \mathbb{R}^d

Biló, 2018 (trees embedded in a metric space)

Wulff-Nilsen, 2010

Wang and Zhao, 2021 (unicycle graphs and trees embedded in a metric space)

graphs embedded in a metric space

Adding k edges/diameter:

Adding k edges/dilation:

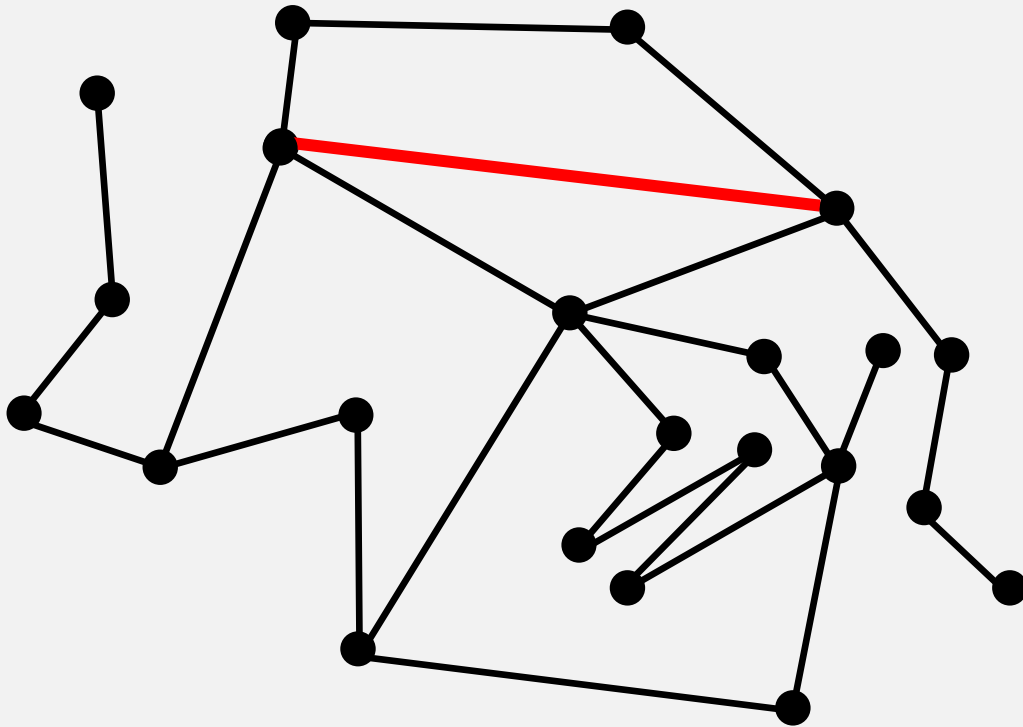
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Gudmundsson and Wong, 2022

graphs embedded in a metric space

Goal: “improve” a graph

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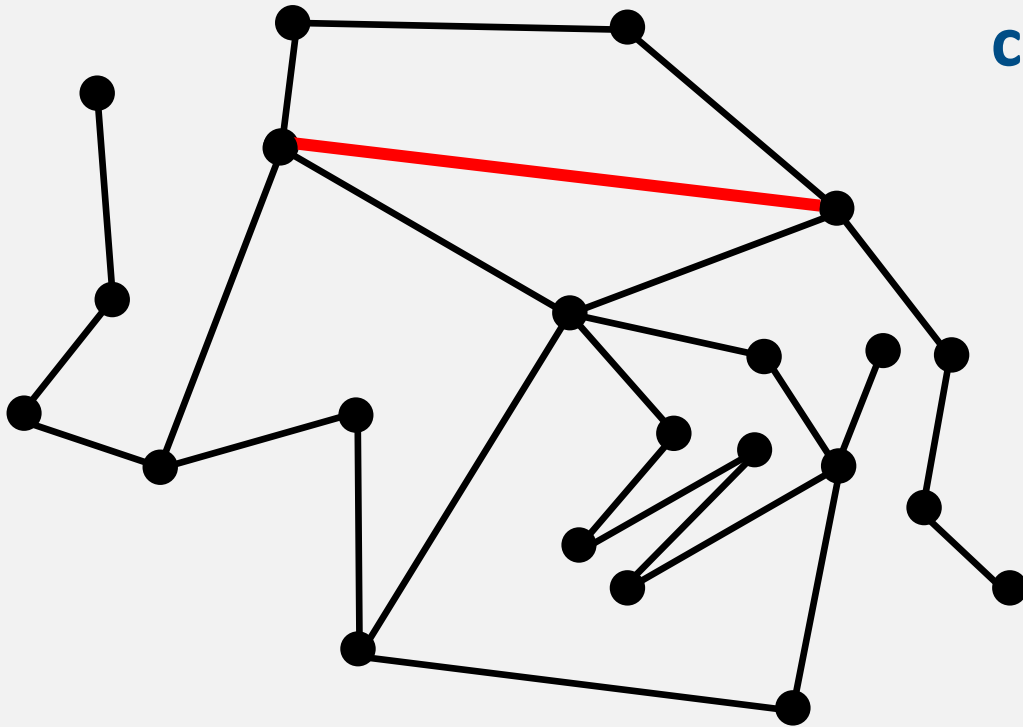


the locus of a graph

Goal: “improve” a graph

~~by adding edges~~

by adding segments
connecting any two points

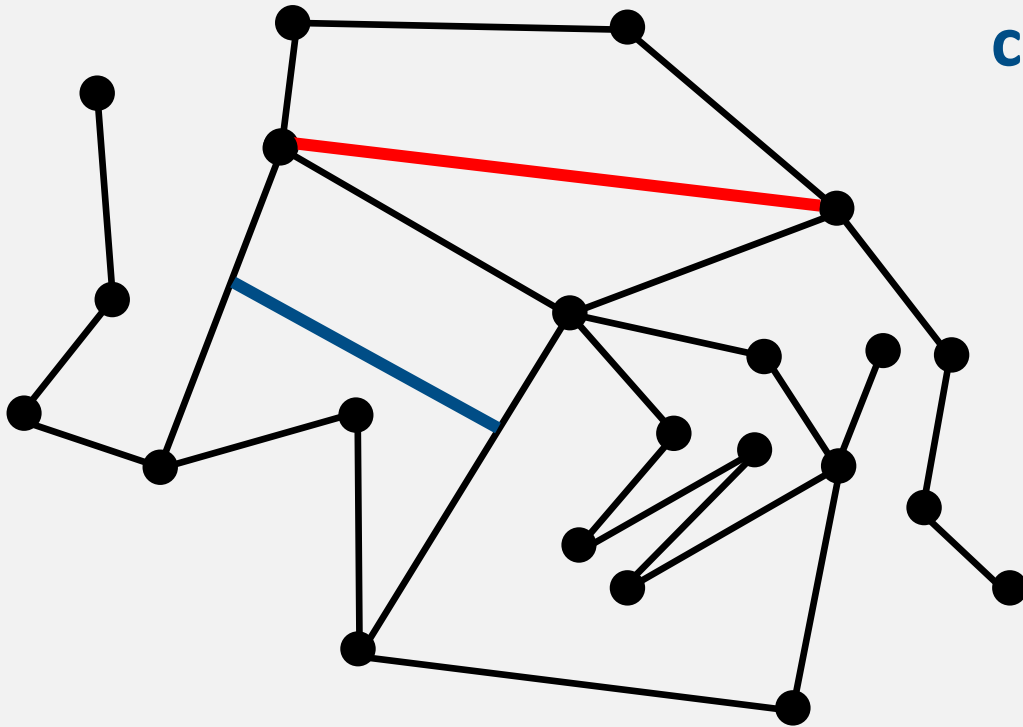


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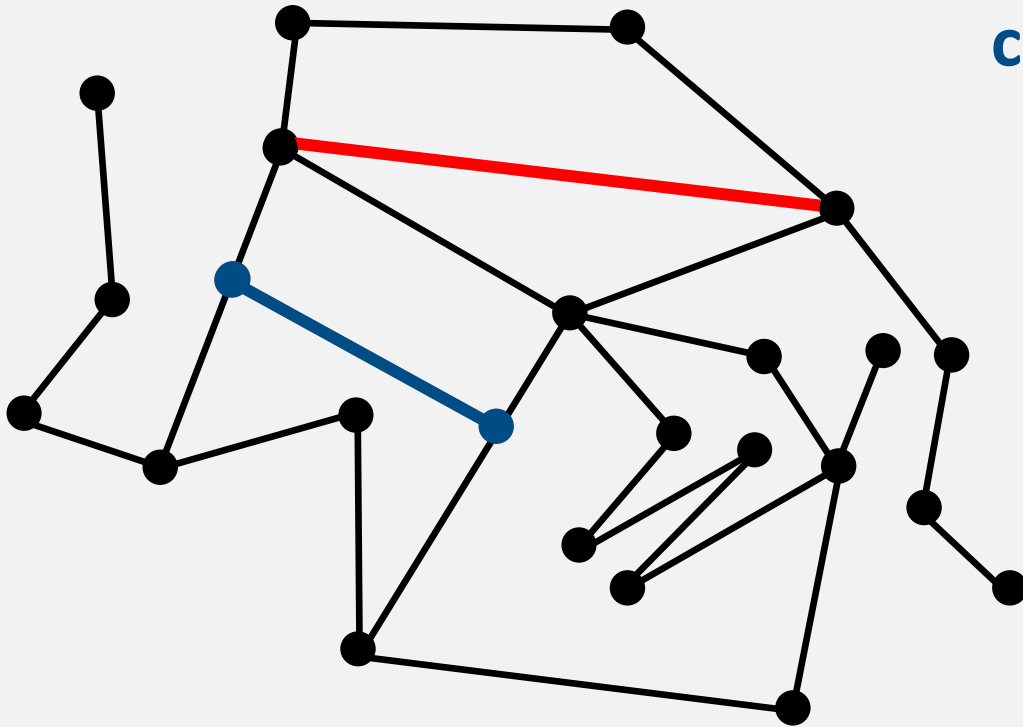


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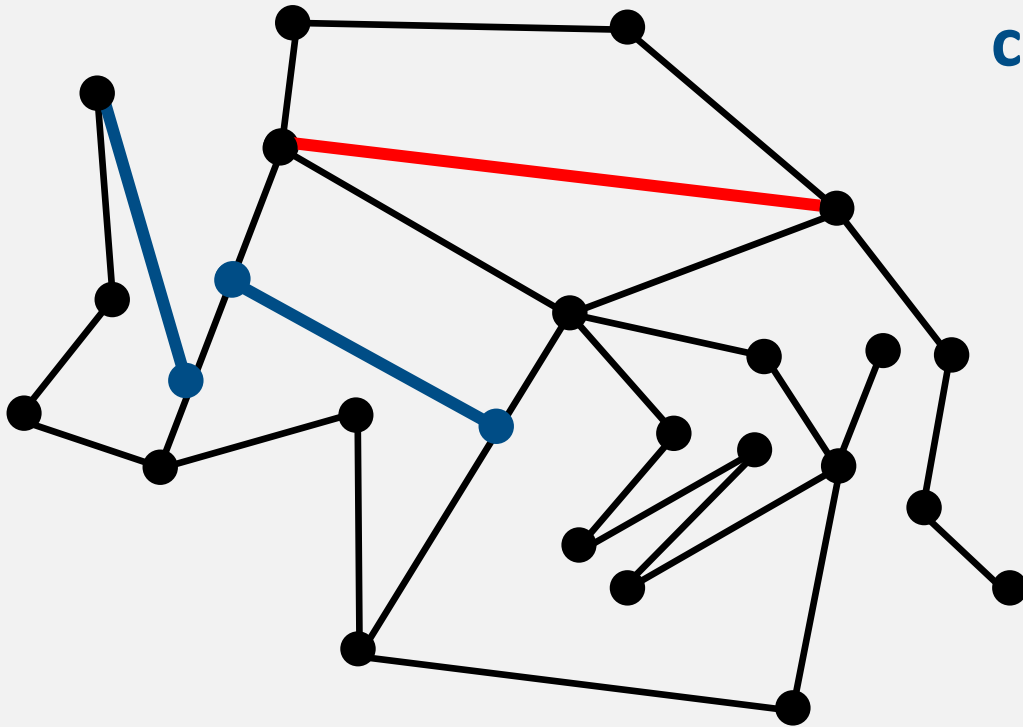


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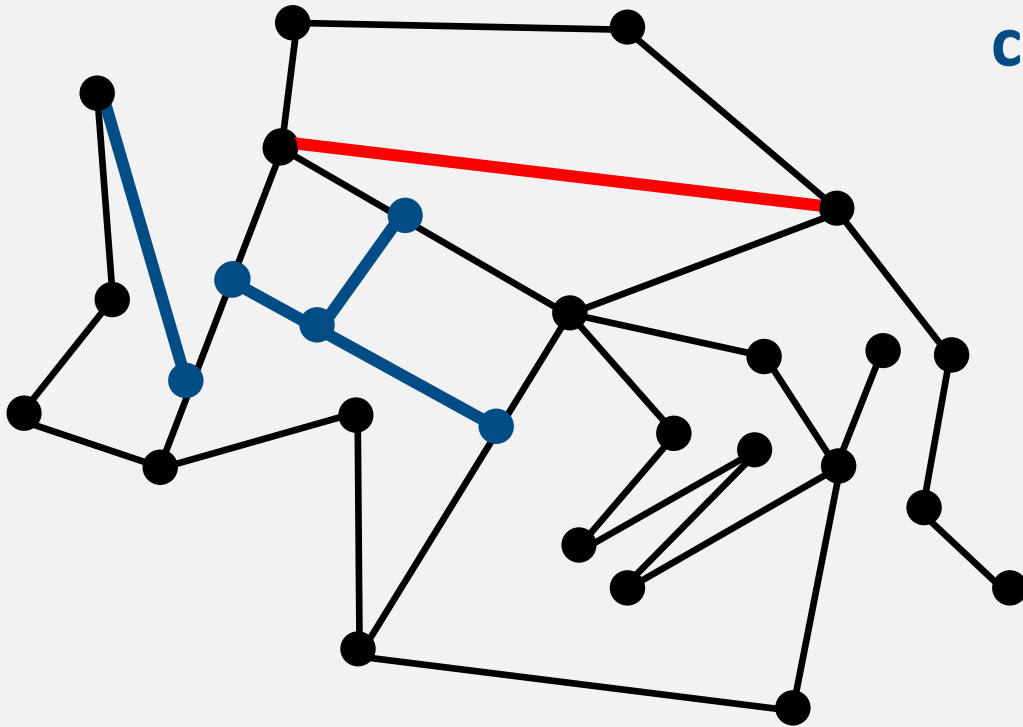


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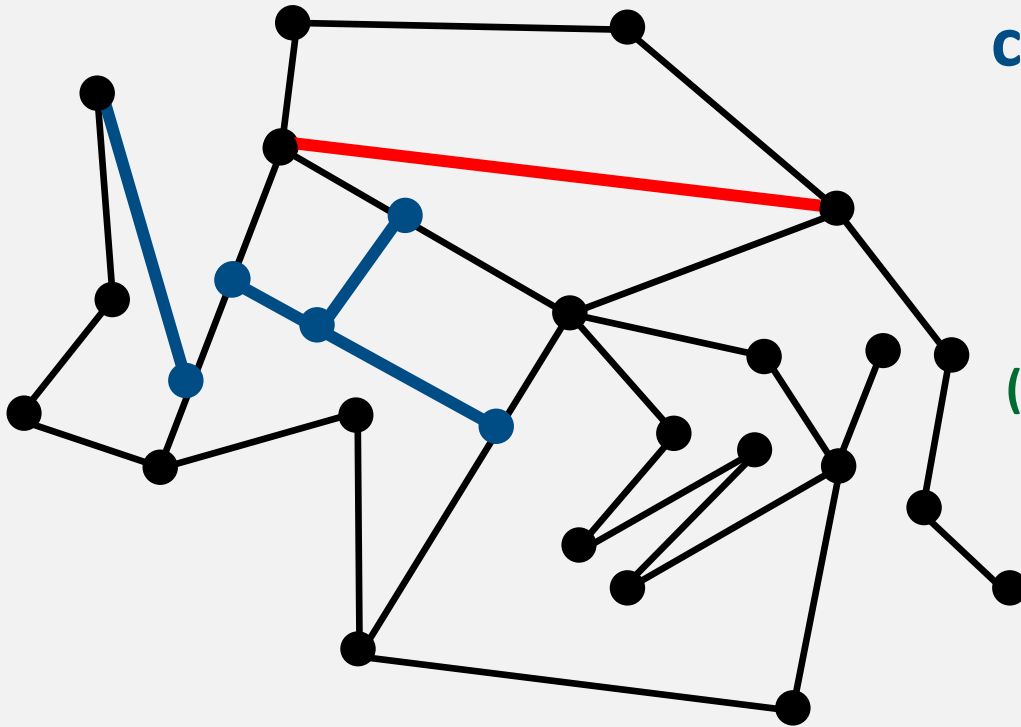


the locus of a graph

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Reduce/minimize:

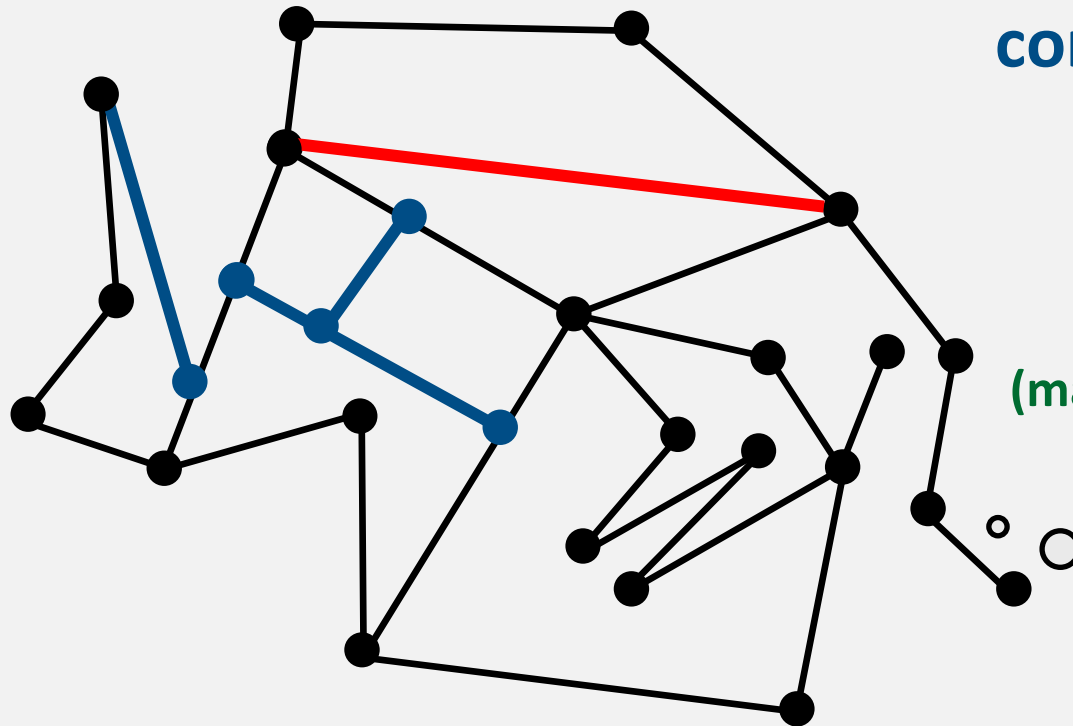
continuous diameter
(max distance between any two points)

the locus of a graph

Goal: “improve” a graph

~~by adding edges~~

by adding segments
connecting any two points



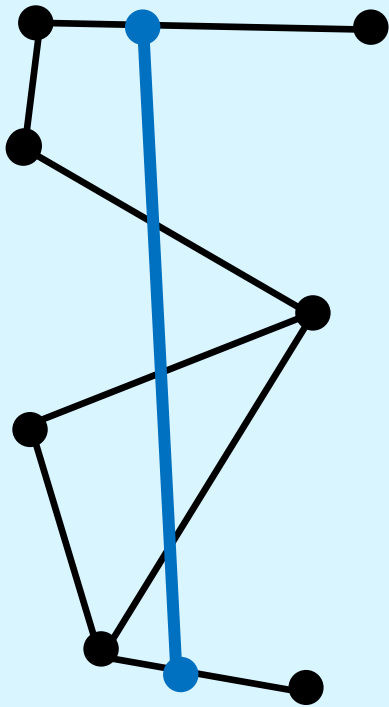
Reduce/minimize:

continuous diameter
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What happens
with crossings?

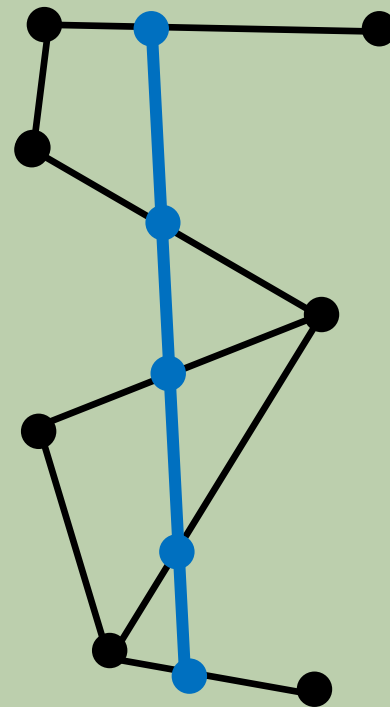
Goal: “improve” a graph

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ignore crossings

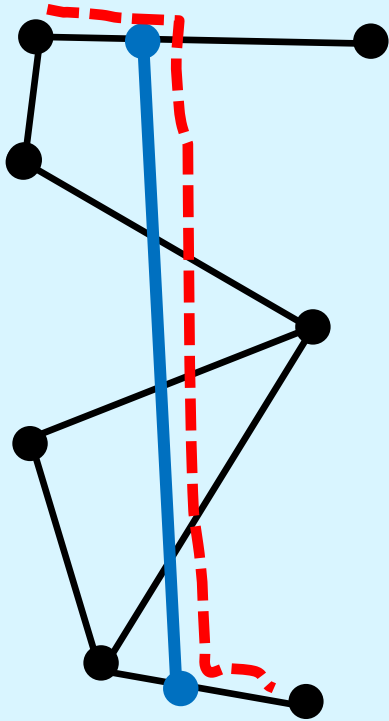
Highway model



Each crossing creates a new vertex

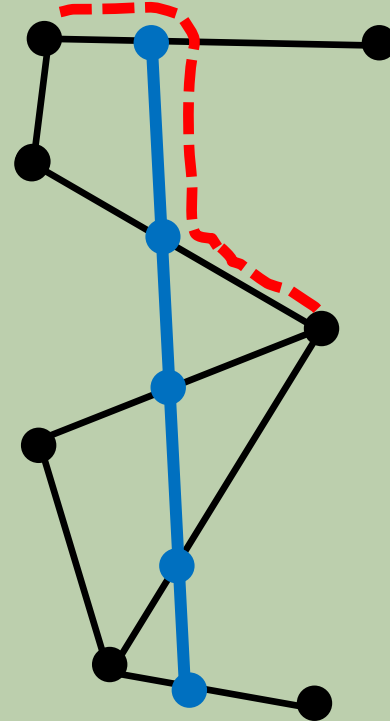
Planar model

Highway model vs. Planar model



ignore crossings

Highway model

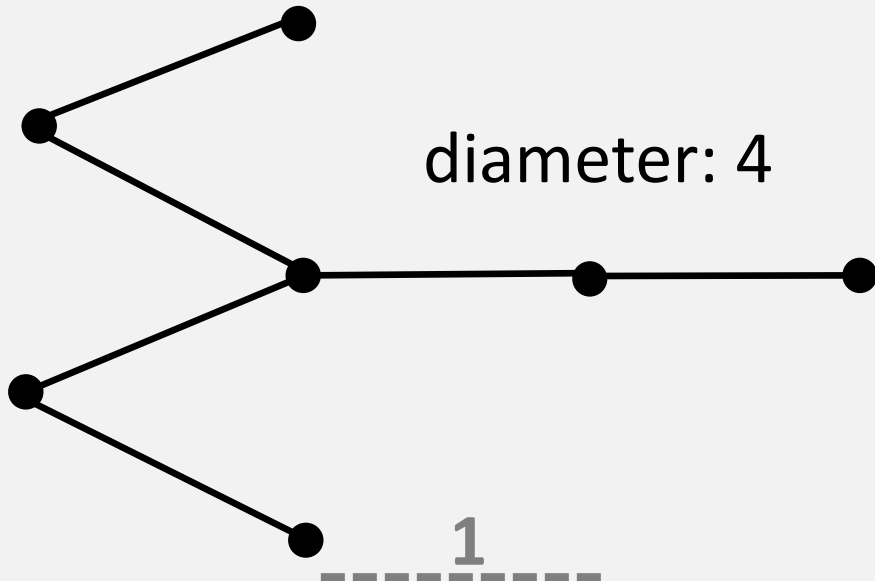


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Planar model

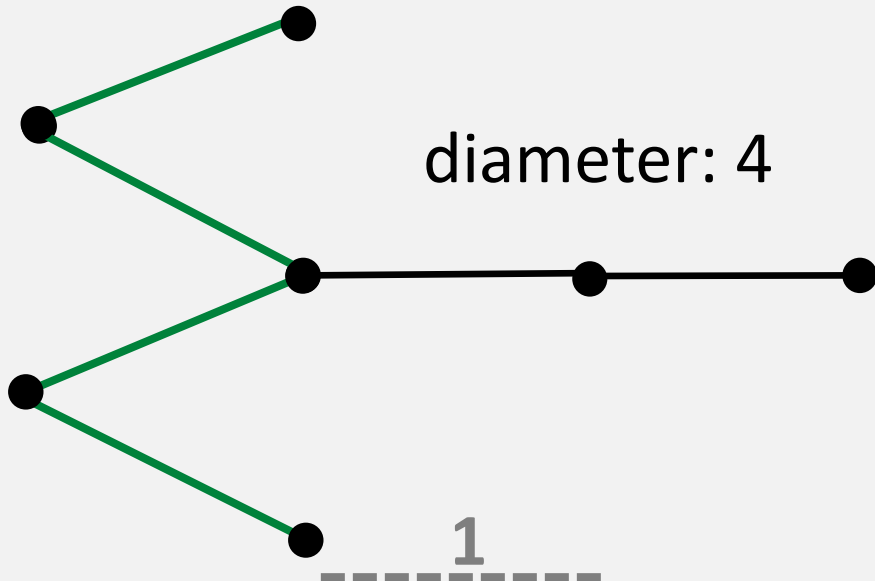
Highway model vs. Planar model

Reduce: **continuous diameter** (max distance between any two points)



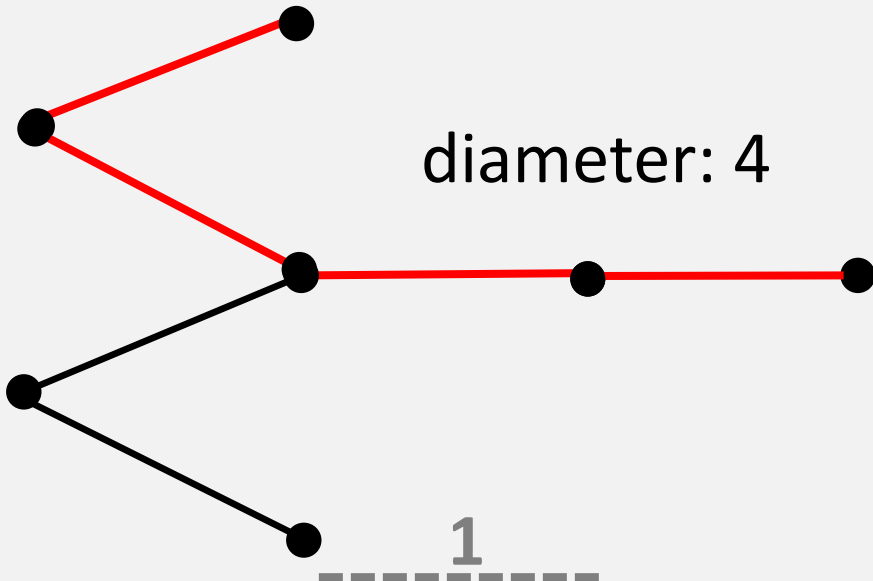
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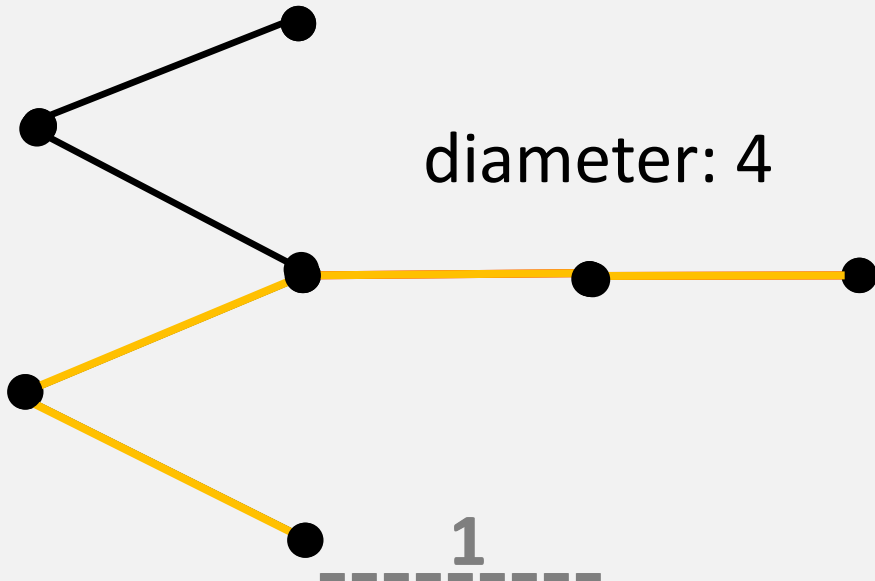
Highway model vs. Planar model

Reduce: **continuous diameter** (max distance between any two points)



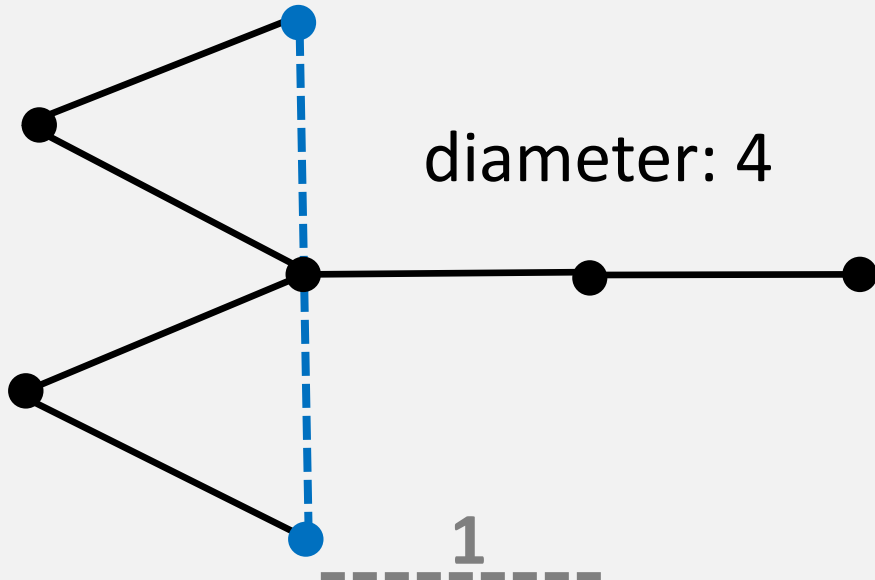
Highway model vs. Planar model

Reduce: **continuous diameter** (max distance between any two points)



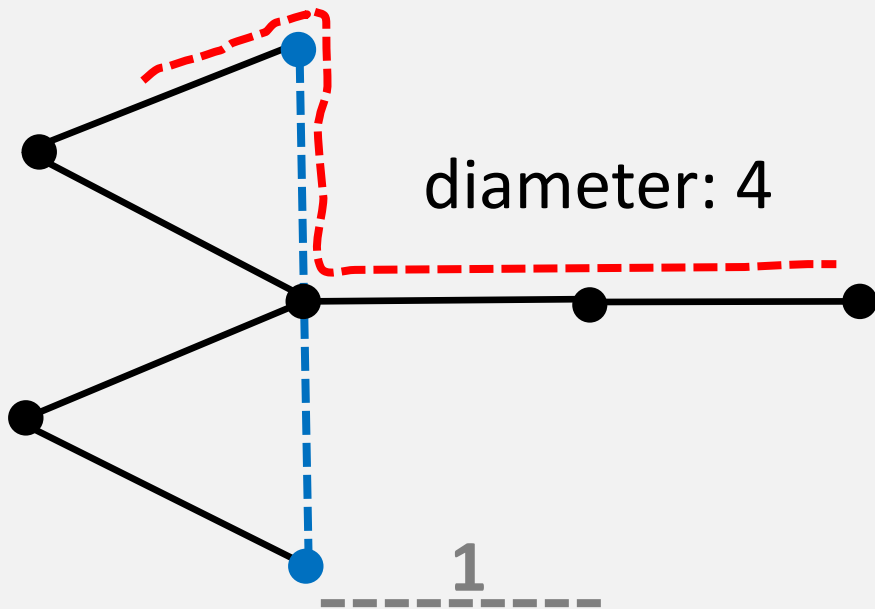
Highway model vs. Planar model

Reduce: **continuous diameter** (max distance between any two points)



Highway model vs. Planar model

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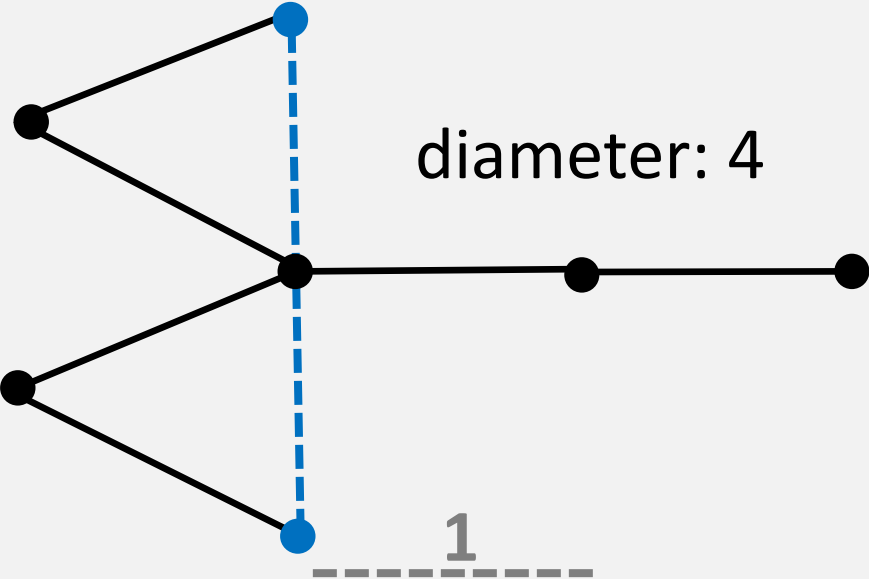


Highway model vs. Planar model

Reduce: **continuous diameter** (max distance between any two points)

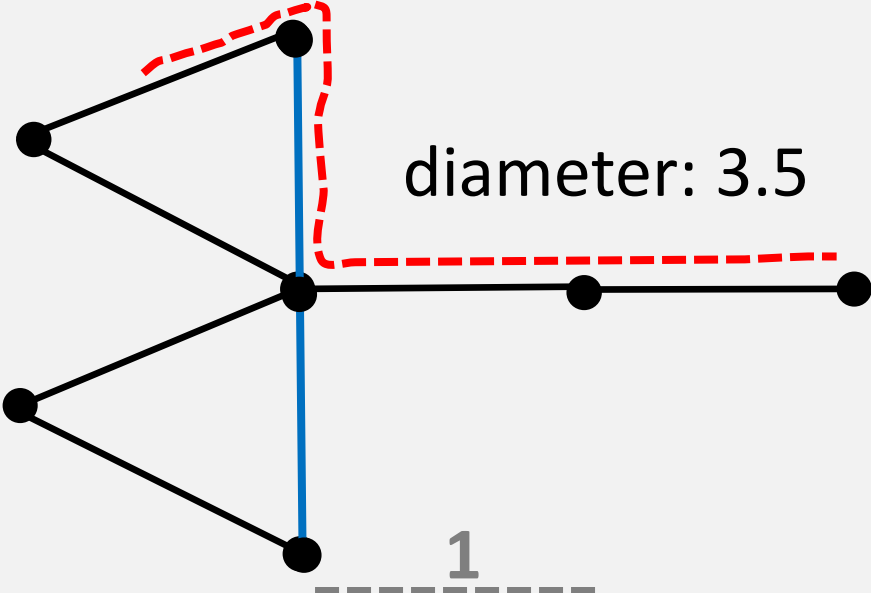
Highway model

No single segment improves diameter



Planar model

diameter improved



Our problem:

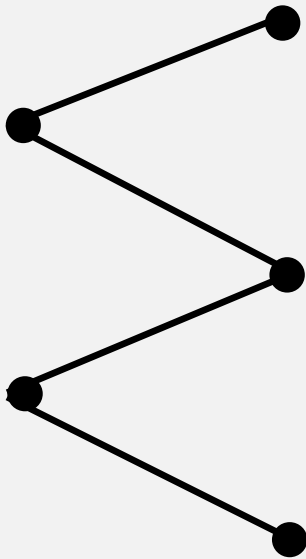
find optimal shortcuts in the **planar model**

Given a graph, find k segments such that in the resulting graph the **continuous diameter** is minimum (over all possible segments)

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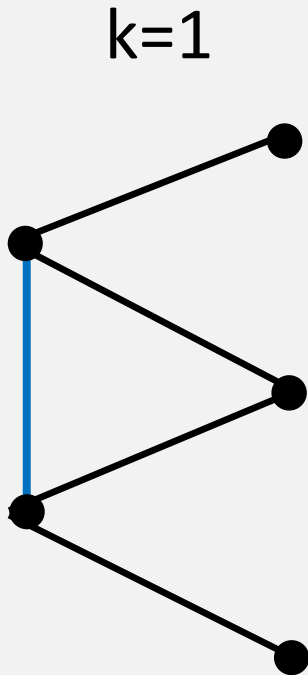
$k=1$



initial diameter: 4

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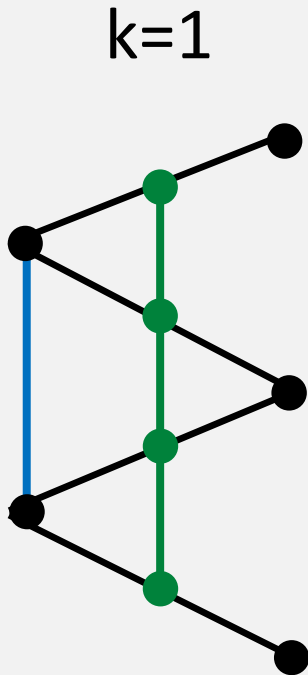


initial diameter: 4

new diameter: 3 → **shortcut: improves**

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initial diameter: 4

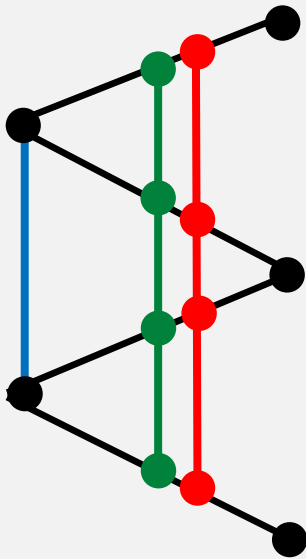
new diameter: 3 → **shortcut: improves**

new diameter: 2.5

Our problem:
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$k=1$



initial diameter: 4

new diameter: 3 → **shortcut: improves**

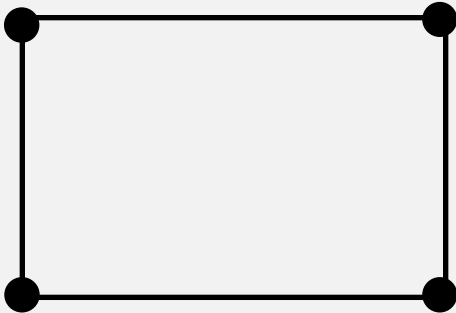
new diameter: 2.5

new diameter: 2.3

→ **optimal shortcut**

Our problem:
find optimal shortcuts in the **planar model**

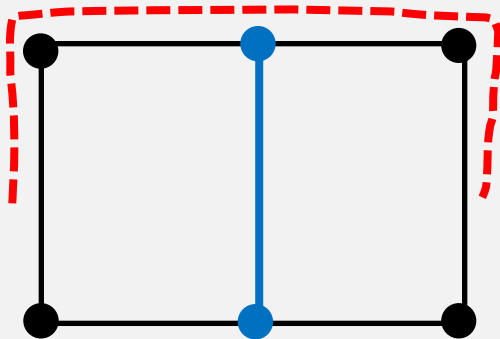
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no single shortcut exists

Our problem:
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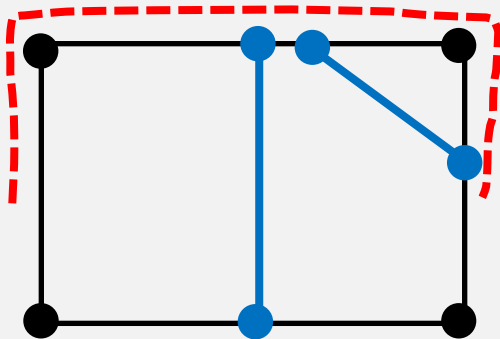
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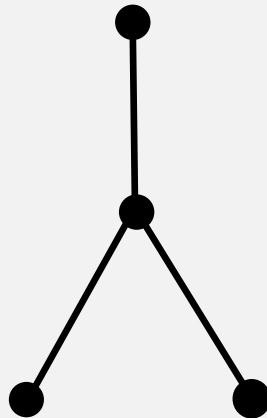


no single shortcut exists
pair of shortcuts ($k=2$)

Our problem:
find optimal shortcuts in the **planar model**

Given a graph, find k segments such that in the resulting graph the **continuous diameter** is minimum (over all possible segments)

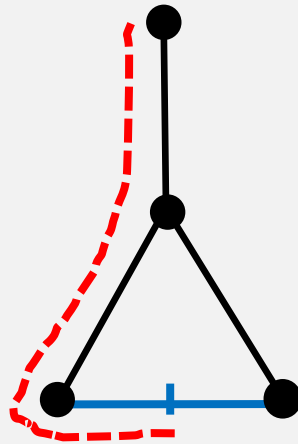
Adding a segment may worsen the diameter!



Our problem:
find optimal shortcuts in the **planar model**

Given a graph, find k segments such that in the resulting graph the **continuous diameter** is minimum (over all possible segments)

Adding a segment may worsen the diameter!



Some results

Minimize: **continuous diameter**

Highway model

Optimal set of k shortcuts:

De Carufel et al. (2016):
geometric paths ($k=1$),
geometric convex cycles ($k=2$)

Oh and Ahn (2016):
weighted trees ($k=1$)

De Carufel et al. (2017):
geometric trees ($k=1$)

Bae et al. (2017):
circles ($k \leq 7$)

Planar model

Approximation algorithms-optimal shortcut ($k=1$)

Yang (2013): certain types of paths

General geometric graphs-optimal shortcut ($k=1$)

G., Márquez, Rodríguez, Silveira (2019)

Some results

Minimize: **continuous diameter**

Planar model

General geometric graphs-optimal shortcut (k=1)

G., Márquez, Rodríguez, Silveira (2019)

- Computation of **optimal shortcut** (k=1) is polynomial
 - Approximation possible via discretization
- } **General graphs**
- Compute diameter after inserting segment $\Theta(n)$
 - Compute optimal horizontal shortcut $O(n^2 \log n)$
 - Compute optimal simple shortcut $O(n^2)$
- } **Paths**

Some results

Minimize: **continuous diameter**

Planar model

General geometric graphs-optimal shortcut (k=1)

G., Márquez, Rodríguez, Silveira (2019)

How fast can an optimal shortcut in general graphs be computed?

Some results

Minimize: **continuous diameter**

Planar model

General geometric graphs-optimal shortcut (k=1)

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How fast can an optimal shortcut in ~~general graphs~~ be computed?
in paths? (any orientation)
in trees?

Some results

Minimize: **continuous diameter**

Planar model

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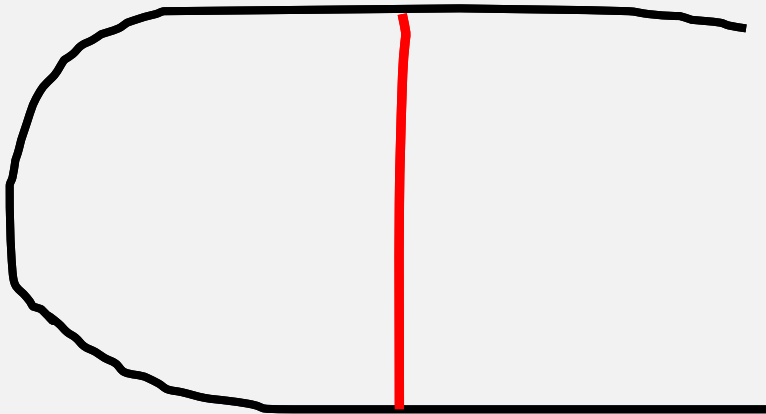
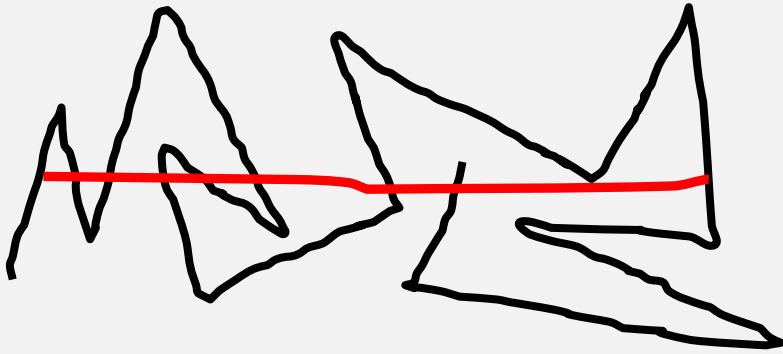
Existence of shortcuts in general geometric graphs

G., Klute, Márquez, Parada, Silveira (2023)

- It is 3SUM-hard to decide if a graph admits a shortcut (k=1)
- It is NP-complete and APX-hard to decide if a graph admits a set of k shortcuts

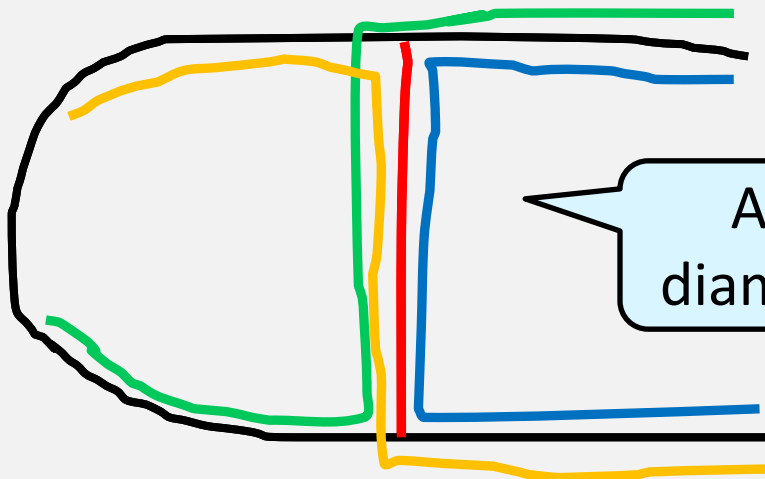
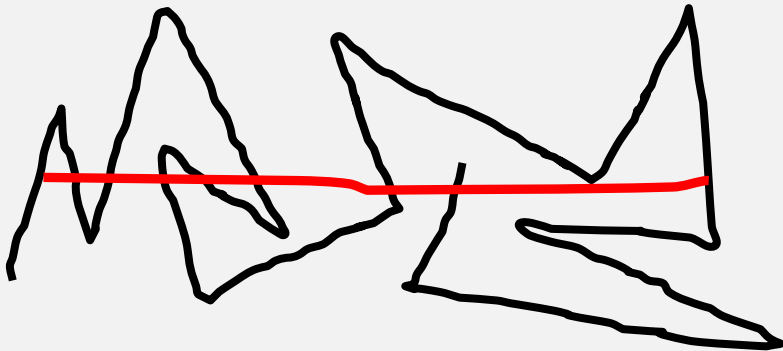
Paths: not so simple

Highway model: no crossings



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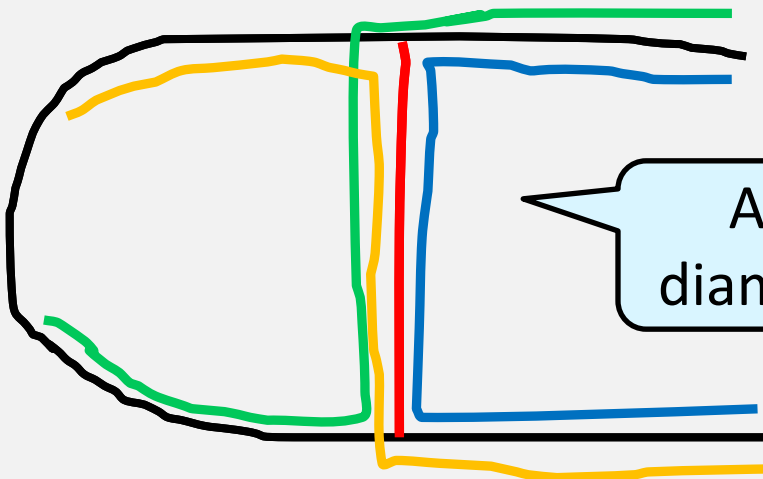
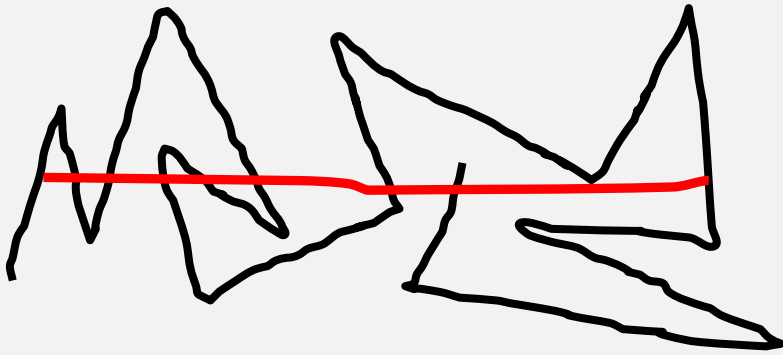
Highway model: no crossings



At most 3
diametral pairs

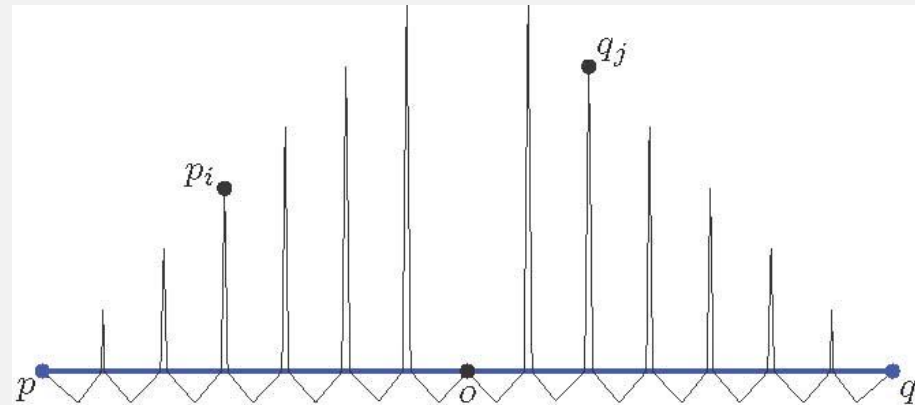
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At most 3
diametral pairs

Planar model



Quadratic number
of diametral pairs

Computation of the continuous diameter

(G., Márquez, Silveira, 2018 and 2023): the **continuous diameter** of a plane geometric graph and the **continuous mean distance** of a plane weighted graph can be computed in quadratic time.

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Cabello (2017): Subquadratic algorithms for the **diameter** and the **sum of pairwise distances** in planar graphs

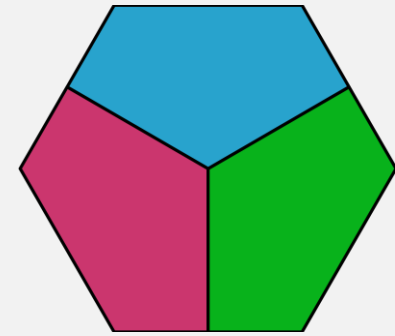
Computation of the continuous diameter

(G., Márquez, Silveira, 2018 and 2023): the **continuous diameter** of a plane geometric graph and the **continuous mean distance** of a plane weighted graph can be computed in quadratic time.

SUBQUADRATIC???
graphs with bounded treewidth

Cabello (2017): Subquadratic algorithms for the **diameter** and the **sum of pairwise distances** in planar graphs

Other type of problem: Borsuk number



Is it true that every set in \mathbb{R}^n can be partitioned into $n + 1$ closed (sub)sets of smaller diameter?

Answered in the positive for:

$n = 2$, Borsuk (1932)

$n = 3$, Perkal (1947)

All n for smooth convex bodies, Hadwiger (1946)

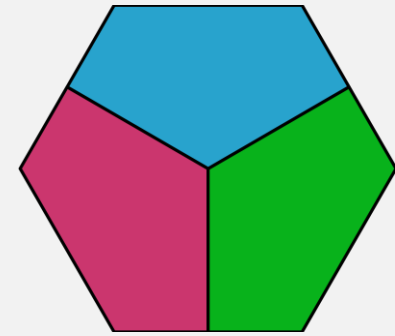
All n for centrally-symmetric bodies, Riesling (1971)

All n for bodies of revolution, Dekster (1995)

The general answer is NO, Kahn and Kalai (1993)

Their construction shows that $n + 1$ pieces do not suffice for $n > 2014$

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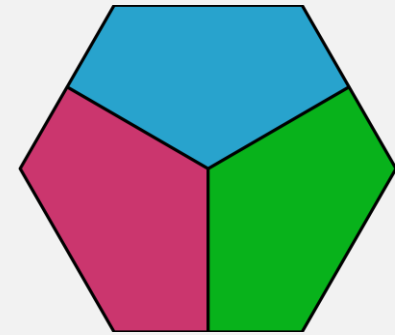
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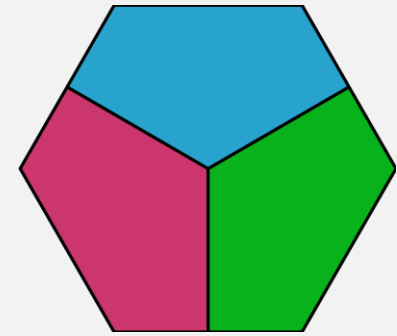
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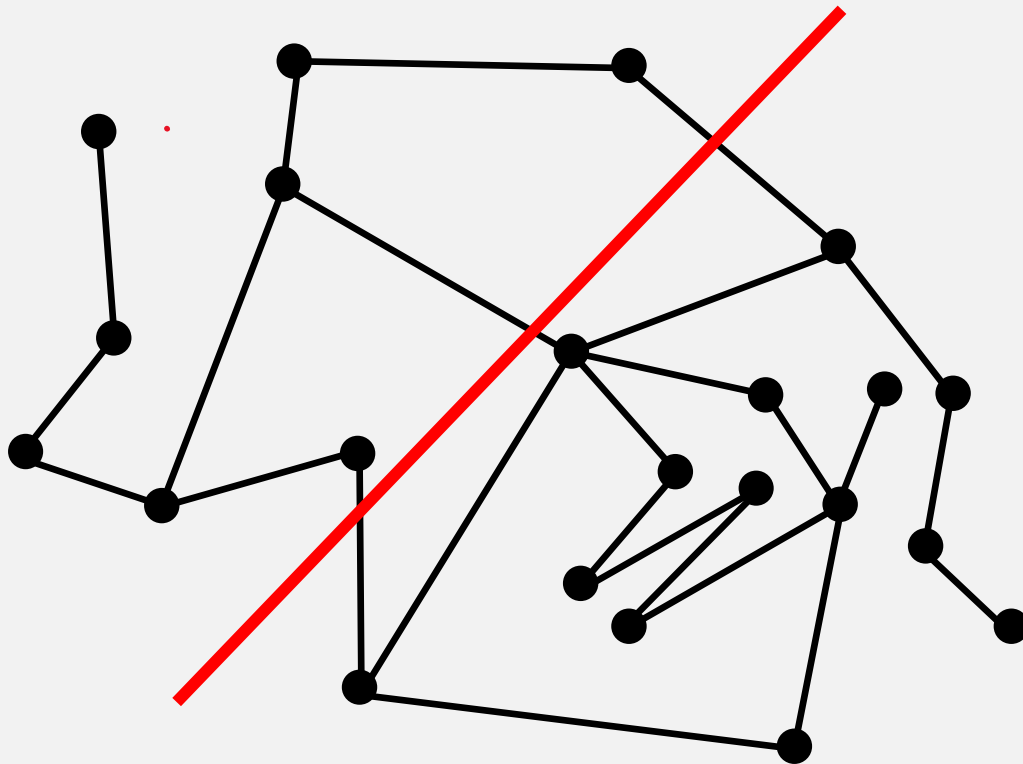
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Borsuk number: #pieces needed to obtain
 $\max\{\text{diameters}\} < \text{original diameter}$

Other type of problem: Borsuk number

Borsuk number

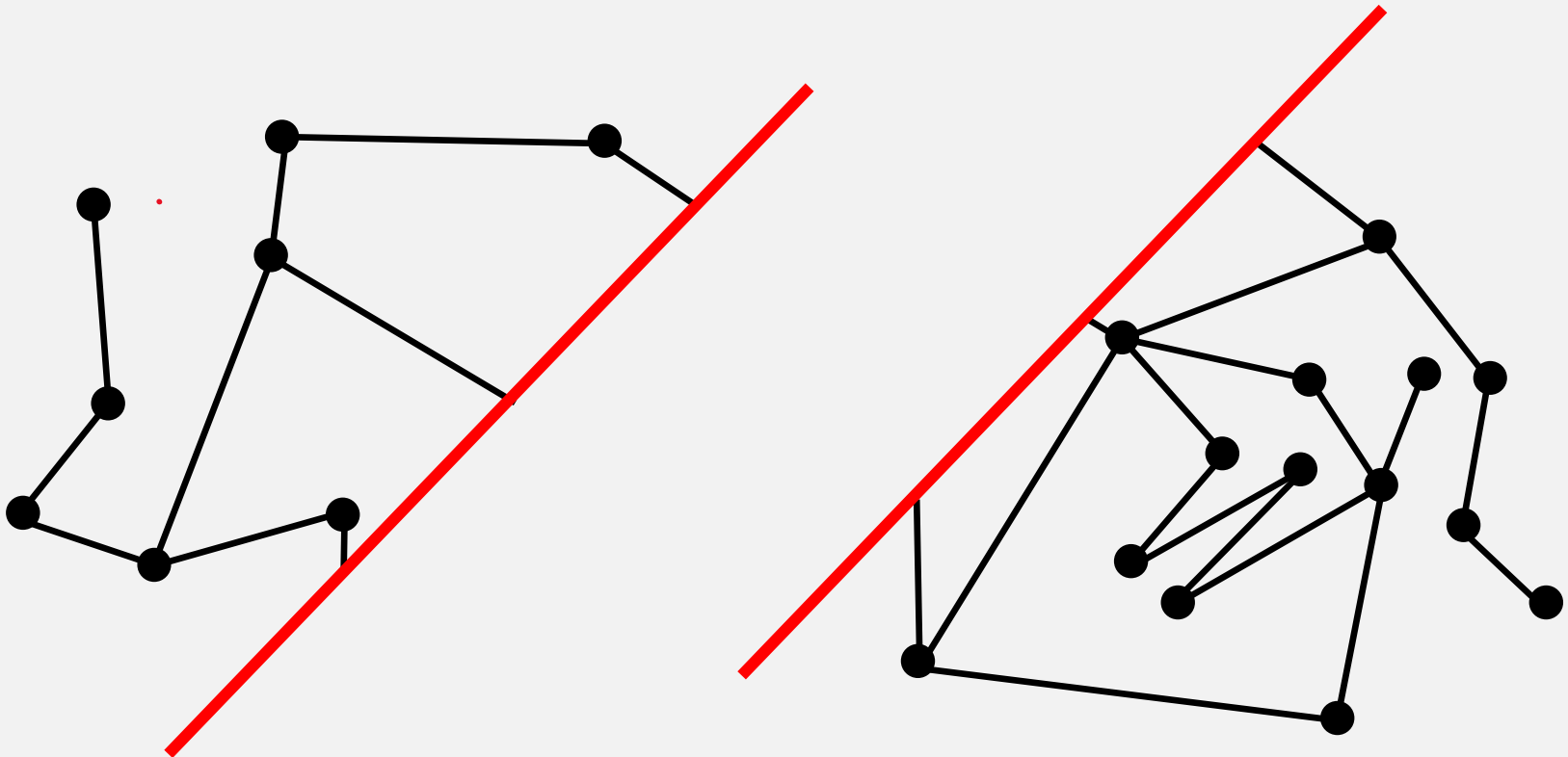
minimum number of connected components to obtain (after cutting by lines) :
 $\max\{\text{continuous diameters}\} < \text{original continuous diameter}$



Other type of problem: Borsuk number

Borsuk number

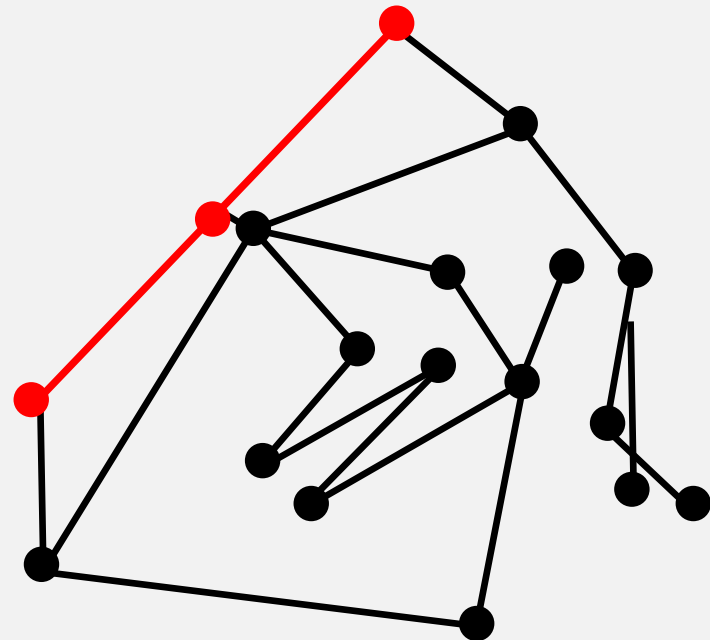
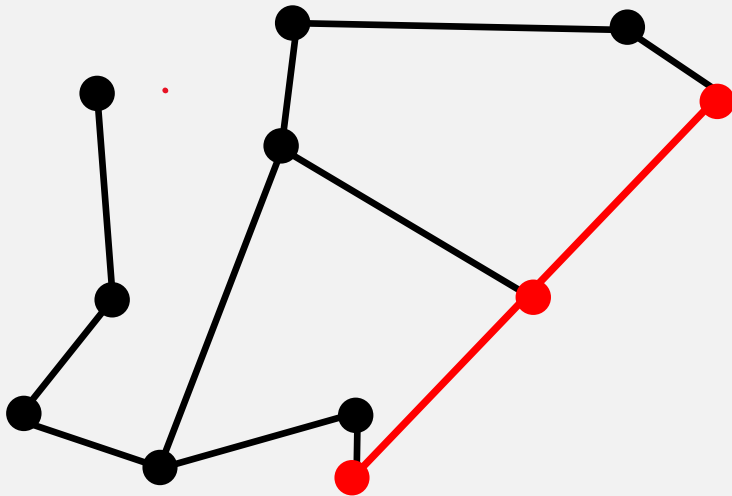
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Other type of problem: Borsuk number

Borsuk number

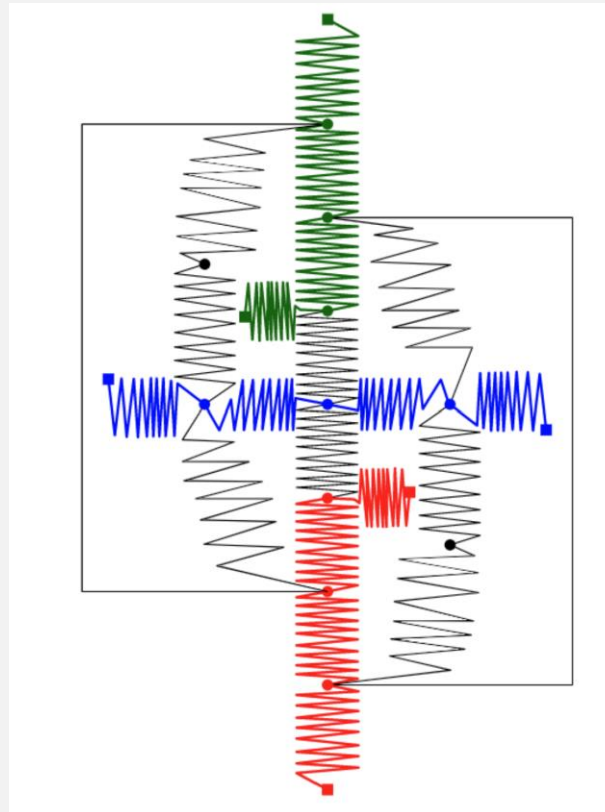
minimum number of connected components to obtain (after cutting by lines) :
 $\max\{\text{continuous diameters}\} < \text{original continuous diameter}$



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Gracias